# Package 'waydown'

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Type Package

<b>Title</b> Computation of Approximate Potentials for Weakly Non-Gradient Fields
Version 1.1.0
Author Pablo Rodríguez-Sánchez
Maintainer Pablo Rodríguez-Sánchez <pablo.rodriguez.sanchez@gmail.com></pablo.rodriguez.sanchez@gmail.com>
Description Computation of approximate potentials for both gradient and non gradient fields. It is known from physics that only gradient fields, also known as conservative, have a well defined potential function. Here we present an algorithm, based on the classical Helmholtz decomposition, to obtain an approximate potential function for non gradient fields.  More information in  Rodríguez-Sánchez (2020) <doi:10.1371 journal.pcbi.1007788="">.</doi:10.1371>
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Encoding UTF-8
LazyData true
RoxygenNote 7.1.1
VignetteBuilder knitr
<b>Suggests</b> testthat, knitr, rmarkdown, deSolve, dplyr, colorRamps, ggplot2, gridExtra, latticeExtra, bindrcpp
Imports numDeriv, Matrix
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approxPot1D

Approximate potential in one dimension

## **Description**

Approximate potential in one dimension

## Usage

```
approxPot1D(f, xs, V0 = "auto")
```

## Arguments

f One-dimensional representing the flow (right hand side of differential equation)

vs Vector of positions to evaluate

V0 (Optional) Value of V at first element of xs. When default, the global minimum

is assigned 0

#### Value

The potential estimated at each point in xs

#### Author(s)

```
Pablo Rodríguez-Sánchez (https://pabrod.github.io)
```

#### References

```
https://arxiv.org/abs/1903.05615
```

#### See Also

```
approxPot2D, deltaV
```

## **Examples**

```
# Flow
f = function(x) { sin(x) }

# Sampling points
xs <- seq(0, 2*pi, length.out = 1e3)

# Approximated potential
Vs <- approxPot1D(f, xs)</pre>
```

approxPot2D 3

approxPot2D
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Approximate potential in two dimensions

## **Description**

Approximate potential in two dimensions

## Usage

```
approxPot2D(f, xs, ys, V0 = "auto", mode = "mixed")
```

## **Arguments**

f	Two-dimensional representing the flow (right hand side of differential equation)
xs	Vector xs positions to evaluate
ys	Vector of ys positions to evaluate
V0	(Optional) Value of V at first element of (xs,ys). When default, the global minimum is assigned $\boldsymbol{0}$
mode	(Optional) Integration mode. Options are horizontal (default), vertical and mixed

#### Value

The potential estimated at each point (xs, ys)

## Author(s)

```
Pablo Rodríguez-Sánchez (https://pabrod.github.io)
```

#### References

```
https://arxiv.org/abs/1903.05615
```

## See Also

```
approxPot1D, deltaV
```

## **Examples**

```
# Flow
f = function(x) {c(-x[1]*(x[1]^2 - 1.1), -x[2]*(x[2]^2 - 1))}
# Sampling points
xs <- seq(-1.5, 1.5, length.out = 10)
ys <- seq(-1.5, 1.5, length.out = 15)
# Approximated potential
Vs <- approxPot2D(f, xs, ys, mode = 'horizontal')</pre>
```

4 deltaV

deltaV

Approximate potential difference between two points

## Description

Approximate potential difference between two points

#### Usage

```
deltaV(f, x, x0, normType = "f")
```

## Arguments

f Flow equations (right hand side of differential equation)
x Position where we want to know the approximate potential
x0 Reference position (center of the Taylor expansion)
normType (default: 'f') Matrix norm used to compute the error

#### Value

A list containing the approximate potential difference between x and x0 and the estimated error

#### Author(s)

```
Pablo Rodríguez-Sánchez (https://pabrod.github.io)
```

#### References

```
https://arxiv.org/abs/1903.05615
```

#### See Also

```
approxPot1D, approxPot2D, norm
```

## **Examples**

```
# One dimensional flow
f <- function(x) { cos(x) }
# Evaluation points
x0 <- 1
x1 <- 1.02
dV <- deltaV(f, x1, x0)
# Two dimensional flow
f <- function(x) { c(
    -2*x[1]*x[2],</pre>
```

deltaV 5

```
-x[1]^2 - 1
)}

# Evaluation points
x0 <- matrix(c(1,2), ncol = 1)
x1 <- matrix(c(0.98,2.01), ncol = 1)
dV <- deltaV(f, x1, x0)
```

## **Index**

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\begin{array}{l} {\rm approxPot1D,\,2,\,\textit{3,\,4}} \\ {\rm approxPot2D,\,2,\,3,\,4} \\ \\ {\rm deltaV,\,2,\,3,\,4} \\ \\ {\rm norm,\,4} \end{array}
```